

center of gravity of container changes from -1396 mm to -121 mm, while the Y -coordinate changes from 2510 mm to 3147 mm.

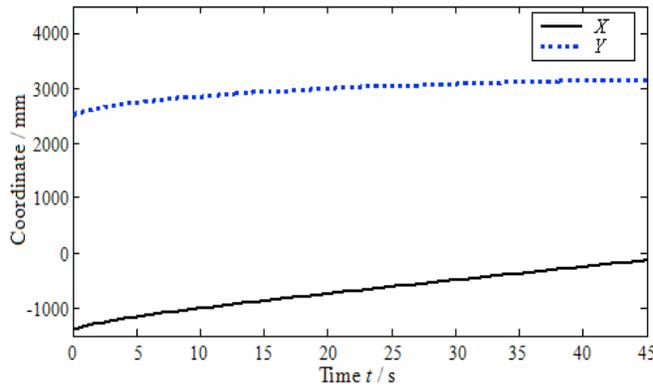


Fig. (11). Position curve of the center of gravity of garbage container.

During garbage dumping, the Y -coordinate of the highest point of the container (t upper left point) is shown in Fig. (12). For various working conditions, the highest point is found during garbage dumping. When the lifting cylinder stretches completely, the upper left point of the garbage container has the maximum Y -coordinate of 6028 mm. That is to say, the maximum height above the ground is 6028 mm.

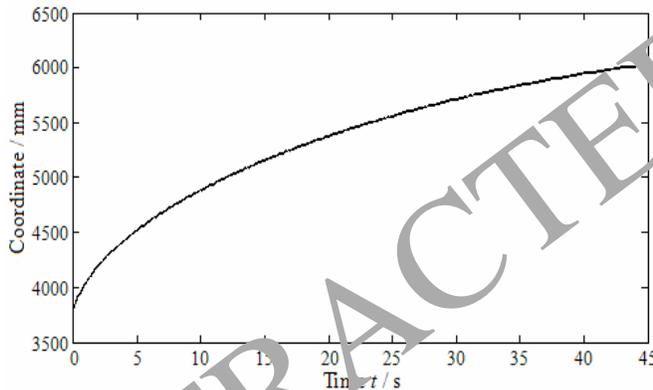


Fig. (12). Y coordinate of the highest point of the garbage container.

The force acting on the lifting cylinder during garbage dumping is shown in Fig. (13). The maximum force of 5.49×10^5 N acting on the lifting cylinder occurs at the initial time during garbage dumping. The force gradually reduces to 8195 N as the lifting cylinder stretches.

CONCLUSION

- (1) The kinematic and mechanical models of the lifting mechanism are analyzed during the two stages of unloading and under the working condition of garbage dumping.

- (2) Using 20 T swing arm DCG truck as an example, the kinematics and force conditions of the lifting mechanism are calculated and analyzed.

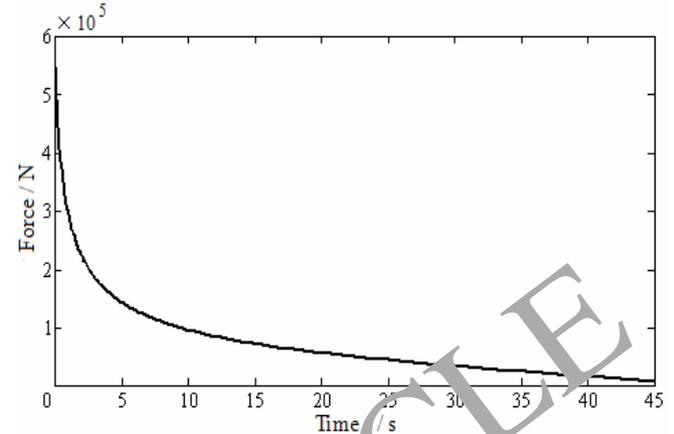


Fig. (13). Force curve of the lifting cylinder.

CONFLICT OF INTEREST

The authors confirm that this article content has no conflict of interest.

ACKNOWLEDGEMENTS

Project (2014QNB18) supported by the Fundamental Research Funds for the Central Universities of China.

REFERENCES

- [1] Tao Sun, Qing Zhang and Ming Liu, "Design & research of large height lifting mechanism for ultra-large structures", *Advanced Materials Research*, vol. 255-260, pp.634-638, 2011.
- [2] R. Jiang, D. Liu, Z. Wang, and W. Fan, "Dynamic characteristics simulation for lifting mechanism of dump truck based on virtual prototype", *Applied Mechanics and Materials*, vol. 195-196, pp. 754-757, 2012.
- [3] J. Hu, W. Ding, and H. Deng, "Dynamic modeling and analysis of lifting mechanism for forging manipulator", *Applied Mechanics and Materials*, vol. 278-280, pp. 633-640, 2013.
- [4] S. Zhang, J. Zhang, and X. Li, "Optimal design of the front push rod assembly lifting mechanism on mining dump truck", *J. Zhengzhou Univ. Eng. Sci. (China)*, vol. 34, no. 2, pp. 125-128, 2013.
- [5] Z. Chen, Y. Wen, and Q. Liu, "Efficient global structure analysis of hook-lift device for detachable compartment refuse collection vehicle", *Journal of Xuzhou Institute of Technology (Natural Sciences Edition)*, vol. 28, no. 4, pp. 66-70, 2013.
- [6] X. Wang, Z. Huang, and H. Wang, "Research on characteristics of rotating hooklift", *Machine Design and Research*, vol. 19, no. 5, pp. 80-83, 2003.
- [7] X. Wang, Z. Huang and H. Wang, "Optimization design on rotating hooklift", *Journal of Tongji University*, vol. 31, no. 9, pp. 1077-1081, 2003.
- [8] L. Zhang, "Study on Pull Arm of the Detachable Garbage Truck", M.S. thesis, China University of Mining and Technology, Xuzhou, China, 2012.